

PITP instabilities lectures 7/2016

Mathematical Derivation of M T I

$$\frac{\partial \rho}{\partial t} + \nabla \cdot \rho \vec{v} = 0$$

$$\rho \frac{\partial \vec{v}}{\partial t} + \rho (\vec{v} \cdot \nabla) \vec{v} = \frac{(\nabla \times \mathbf{B}) \times \vec{B}}{4\pi} - \nabla p + \rho \vec{g}$$

$\rightarrow \vec{v} \cdot \nabla$

$$\frac{\partial \vec{B}}{\partial t} = \nabla \times (\vec{v} \times \vec{B})$$

$$\rho T \frac{\partial s}{\partial t} + \rho (\vec{v} \cdot \nabla) s = - \nabla \cdot \vec{Q}$$

Key physics non-adiabatic

$$\vec{Q} = - \chi \vec{b} (\vec{b} \cdot \nabla T)$$

heat fluxes along b

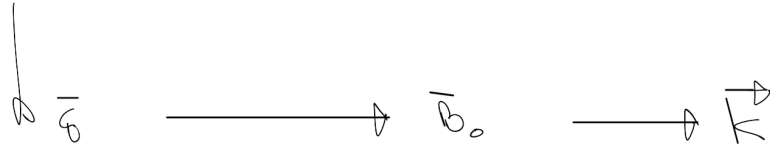
Weak B-field \Rightarrow drop Lorentz force

Boussinesq approx: keep buoyancy $\delta \rho \vec{g}$

but otherwise set $\vec{v} \cdot \nabla = 0$

dropping cont. to $\delta \rho$ from pressure variations (sound waves); only keeping buoyancy .. applies if timescale of instability \gg sound crossing time

Linear perturbation theory with



key is heat flux

$$\delta \vec{Q} = -\chi \delta \hat{b} (\vec{b}_0 \cdot \nabla T) - \chi \vec{b}_0 (\delta \hat{b} \cdot \nabla T) - \chi \vec{b}_0 (\vec{b}_0 \cdot \vec{k}) \delta T$$

$$\hat{b} = \frac{\vec{B}}{|\vec{B}|}$$

here $\nabla \cdot \vec{B} = 0 \Rightarrow$

$$\vec{k} \cdot \delta \vec{B} = 0 \Rightarrow \delta B_x = 0$$

$$\delta \hat{b} = \delta \vec{B} / B_0$$

$$|\vec{B}| = (B_0^2 + 2B_0 \delta B + \delta B^2)^{1/2}$$

$$= B_0 \text{ to linear order}$$

i.e. no change to $|\vec{B}|$

$$\frac{d\vec{B}}{dt} = \nabla \times (\vec{v} \times \vec{B}) = (\nabla \cdot \vec{v}) \vec{B} - (\vec{v} \cdot \nabla) \vec{B}$$

0 in linear theory

$$-\chi \nabla \delta \vec{B} = \chi B_0 \vec{k} \delta v$$

$$\delta \vec{v} = \frac{d\vec{B}}{dt} = -\nu \vec{\zeta} \Rightarrow$$

$$\frac{\delta \vec{B}}{B_0} = i k \vec{\zeta} = \delta \hat{b}$$

$$\delta \bar{q} = \delta q_x = -\chi k \xi_z \frac{dT}{dz} - \chi k \delta T$$

$$\nabla \cdot \delta \bar{q} = \chi k \delta q_x = k^2 \chi \left(\xi_z \frac{dT}{dz} + \delta T \right)$$

rapid thermal conduction \Rightarrow $k^2 \chi \xrightarrow{\text{(conduction time)} \rightarrow 0} \infty$

"shorting out" the heat flux \Rightarrow

$$\delta T + \xi_z \frac{dT}{dz} = 0 \Rightarrow \Delta T = 0 \quad \text{field lines isothermal}$$

pressure equil $\frac{\delta p}{\rho} = 0 = \frac{\delta e}{e} + \frac{\delta T}{T}$

rapid thermal conduction \Rightarrow

$$\frac{\delta e}{e} = \xi_z \frac{d \ln T}{dz}$$

$$\frac{dT}{dz} < 0 \quad \xi_z > 0 \quad \delta e < 0 \quad \text{unstable!}$$

Note: by this reasoning $\frac{dT}{dz} > 0$ stable MTI

HTI Physics

$\frac{dT}{dz} > 0$ hot
cold \downarrow
 $\vec{j} \cdot \vec{B}$

Need $k_x + k_z$

$$\vec{E} \cdot \delta \vec{B} = 0 \Rightarrow k_x \delta B_x + k_z \delta B_z = 0$$

$$\Rightarrow \delta B_z \neq 0$$

$$|\vec{B}| = (B_0^2 + 2\delta \vec{B} \cdot \vec{B}_0 + \dots)^{1/2}$$

$$\Rightarrow \delta |\vec{B}| = \delta B_z \neq 0$$

Same trick as in MTI derivation

let $k_z^2 \chi \rightarrow \infty$ conduction time $\rightarrow 0$

$$\frac{\delta T}{T} = 2 \xi_z \frac{d \ln T}{dz}$$

logarithm

$$\frac{\delta \rho}{\rho} = - \xi_z \frac{d \ln T}{dz}$$

$$\frac{dT}{dz} > 0 \quad \xi_z > 0 \quad \delta \rho < 0$$

buoyantly unstable!

MTI $\delta T/T = 0$ isothermal pert.

here $\delta T/T > 0$ for rising fluid \rightarrow hotter than surroundings \rightarrow buoyant
(tapping into bg. heat flux)

Asymmetric Hydro/MHD Instability Condition

Heuristic Derivation (do detailed linear pert. theory yourself to check this!!)



at position 1

$$l^2(R_1) R_1 = GM(R_1) / R_1^2$$

at position 2

$$l^2(R_2) R_2 = GM(R_2) / R_2^2$$

+ note $l^2 R = l^2 / R^3$

defines equil

after perturbation

$$\begin{aligned} a_{\text{net}}(R_2) &= a_{\text{cent}} - a_{\text{grav}} \\ &= \frac{l^2(R_1)}{R_2^3} - \frac{GM(R_2)}{R_2^2} \end{aligned}$$

assumed here that l is conserved during perturbation which is why $l^2(R_1)$ shows up in cent. force at new position

Taylor expand

$$l^2(R_2) = l^2(R_1) + \frac{dl^2}{dR} \delta R$$

$$\Rightarrow a_{\text{net}}(R_2) = \frac{l^2(R_2)}{R_2^3} - \frac{GM(R_2)}{R_2^2} - \frac{l}{R^2} \frac{dl^2}{dR} \delta R$$

0 by equil. condition

$$\Rightarrow a_{\text{net}} = -l^2 \delta R \text{ as claimed}$$

this can be written as

$$\delta \ddot{R} + \kappa^2 \delta R = 0 \quad \text{unstable if } \kappa^2 < 0 \\ \text{stable if } \kappa^2 > 0$$

MHI calculation is the same except
assume $\Omega = \text{const.}$ (tension \Rightarrow co-rotation
is heuristic argument)

instead of $l = \text{const.}$

$$\text{get } Q_{\text{net}} = - \frac{dL^2}{dlnR} \delta R$$

$$\text{unstable if } \frac{dL^2}{dlnR} < 0$$

MA I instability condition